

Runtime Verification Based on Executable Models: On-the-Fly Matching of Timed Traces

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Outline

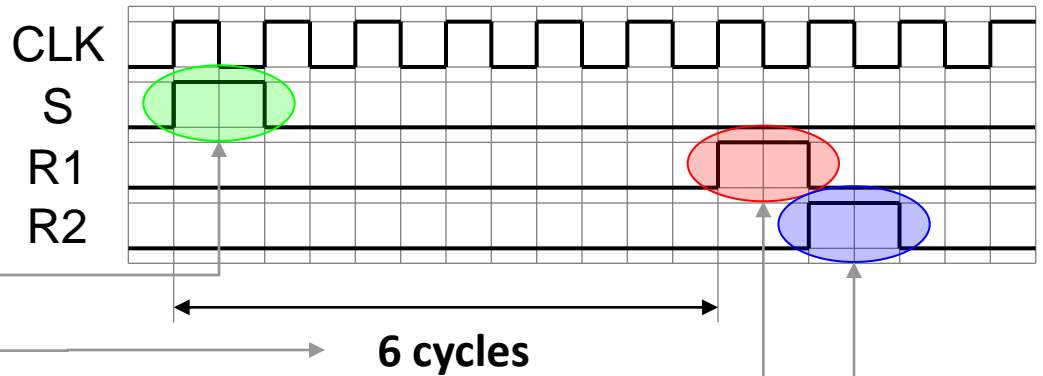
- Hardware models
- Runtime verification
- Elements of formalization
- Conformance relation
- Conclusion

Hardware models

- They are developed in Hardware Description Languages, like Verilog or VHDL
- The result of development is the program being executed in HDL simulator
- The common approach for verification of hardware models is testing of HDL programs
- To automatize testing is possible by means of executable models (e.g. in C++)

HDL programs

```
input S;  
output R1, R2;  
void design() {  
    while(true) {  
        wait(S);  
        delay(6);  
        R1 = 1;  
        delay(1);  
        {  
            R1 = 0;  
            R2 = 1;  
        }  
        delay(1);  
        R2 = 0;  
    }  
}
```

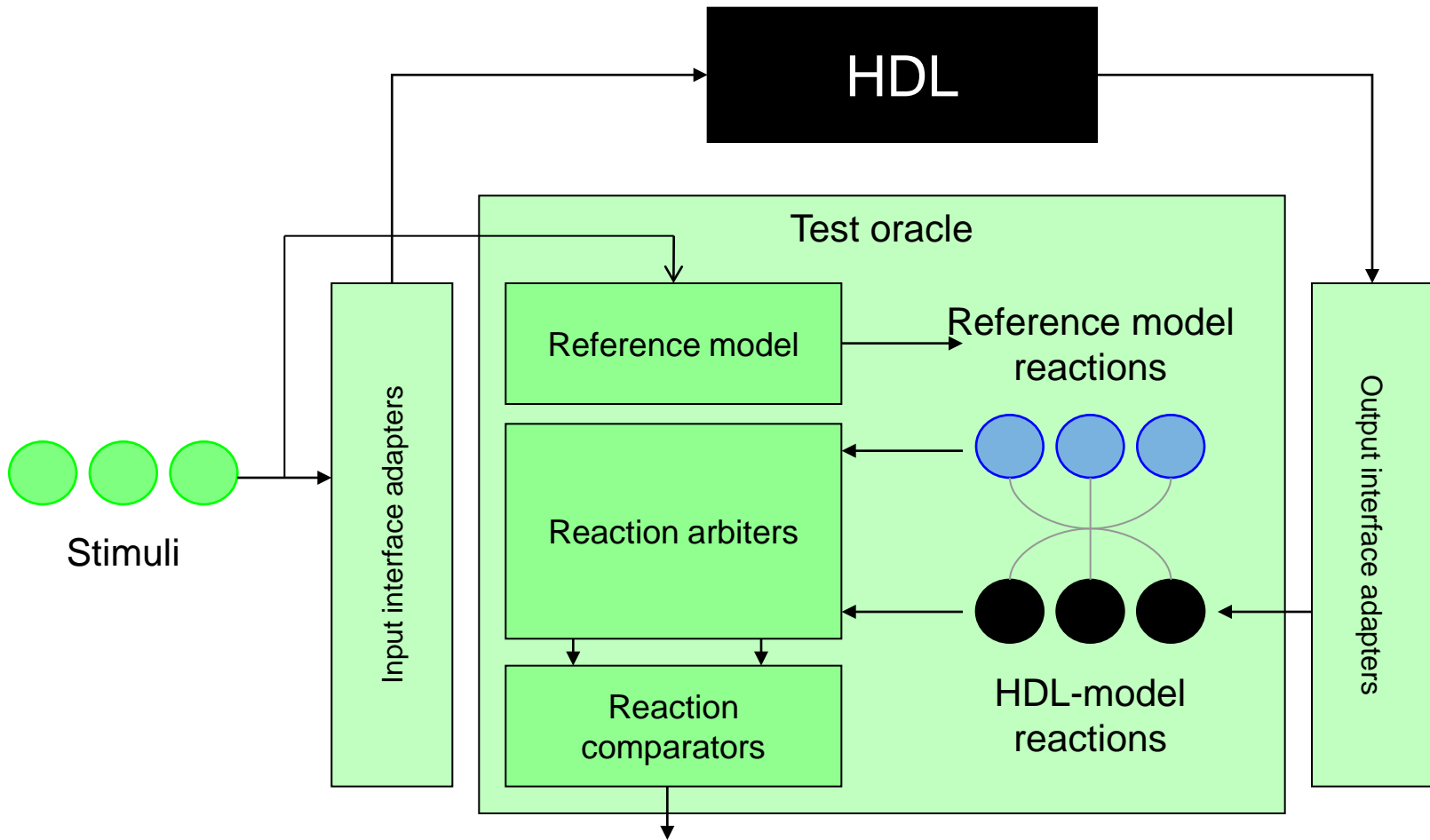


$\left[\begin{array}{l} R1 = 0; \\ R2 = 1; \end{array} \right]$ → **Parallel assignments**

Hardware model behavior



Reference model-based test oracle



Behavior correctness checking

Functional properties

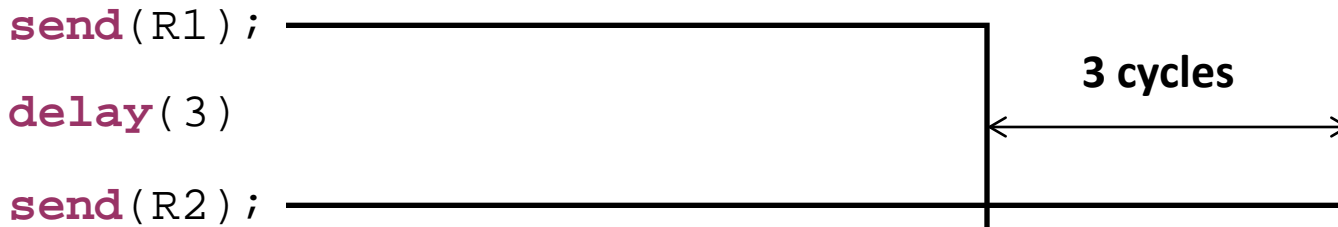
- Set of reactions is correct
- Each reaction is correct

- Reaction order is correct
- Delays between reactions are correct

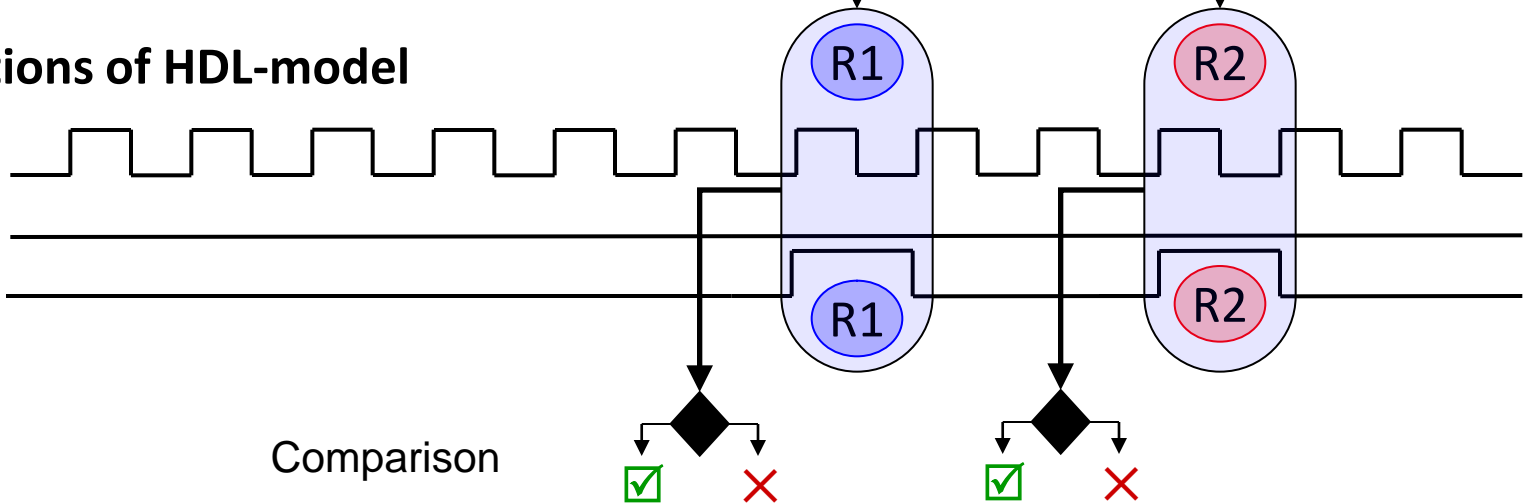
Time restrictions

Cycle-accurate checking

Reference model reactions



Reactions of HDL-model



Ambiguity in reaction order

Execution of reference model

```
recv(in_iface, S);
```

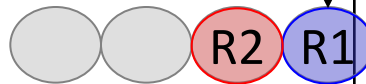
...

```
send(out_iface, R1);
```

...

```
send(out_iface, R2);
```

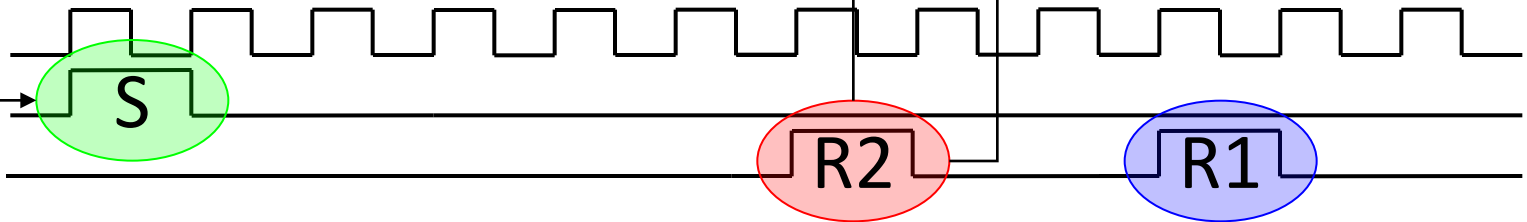
Reaction order



Error: $R2 \neq R1$

Allowed: $R2 \in \text{Order}$

Execution of HDL-model



Reverse order

Arbitration of reactions

- Reaction arbiter finds a reaction corresponding to the reference model one
- Behavior checking depends on both reference model and on arbitration
- Reaction arbiters encapsulate parts of test oracle functionality aimed at reaction order checking

Types of reaction arbiters

- Deterministic model-based arbiter

$$\text{arbiter}: 2^{\text{Reaction}} \rightarrow \text{Reaction} \cup \{\text{fail}\}$$

- Adaptive arbiter

$$\text{arbiter}: 2^{\text{Reaction}} \times \text{Reaction} \rightarrow \text{Reaction} \cup \{\text{fail}\}$$

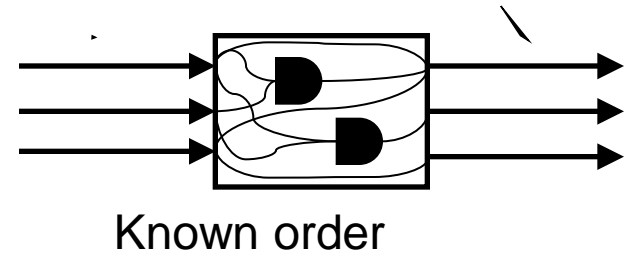
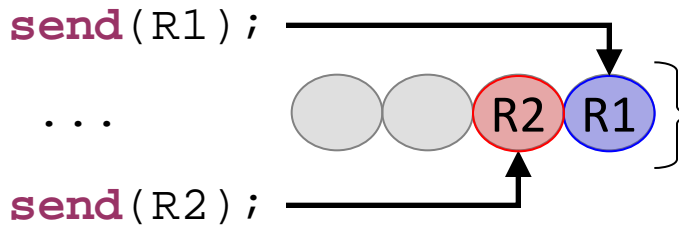
- Two-level arbiter

$$\text{arbiter}(\text{reactions}) \equiv \text{arbiter}_2(\text{arbiter}_1(\text{reactions}), \text{reaction})$$

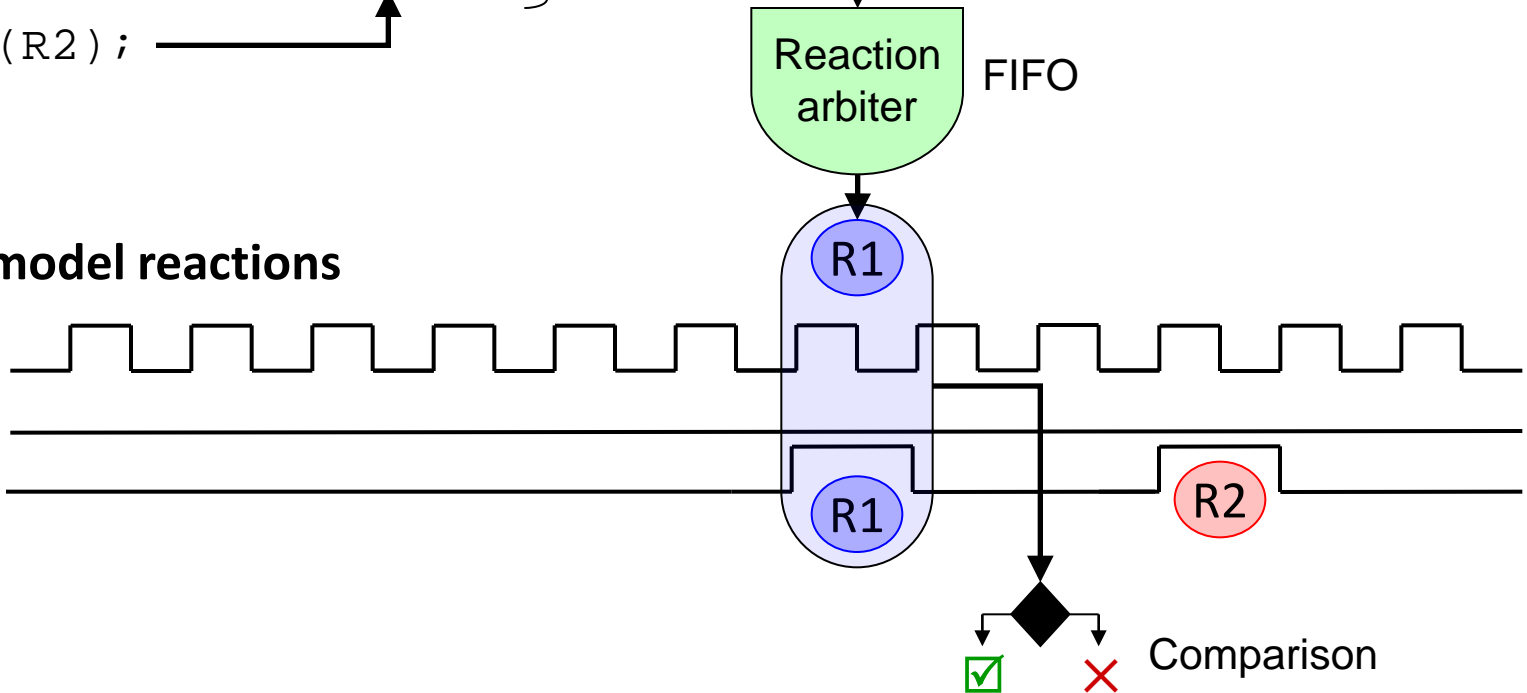
- Non-deterministic arbiter
- Adaptive arbiter

Deterministic arbiter

Reference model reactions

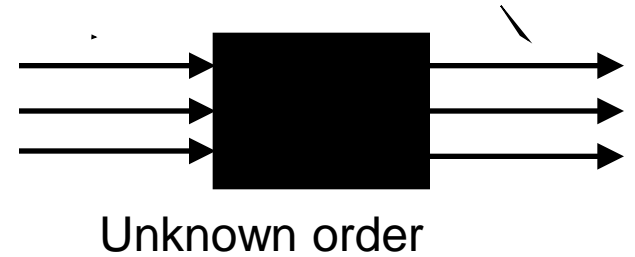
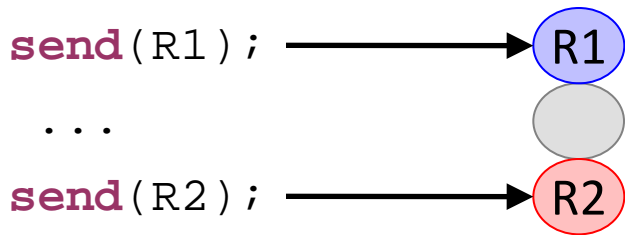


HDL-model reactions

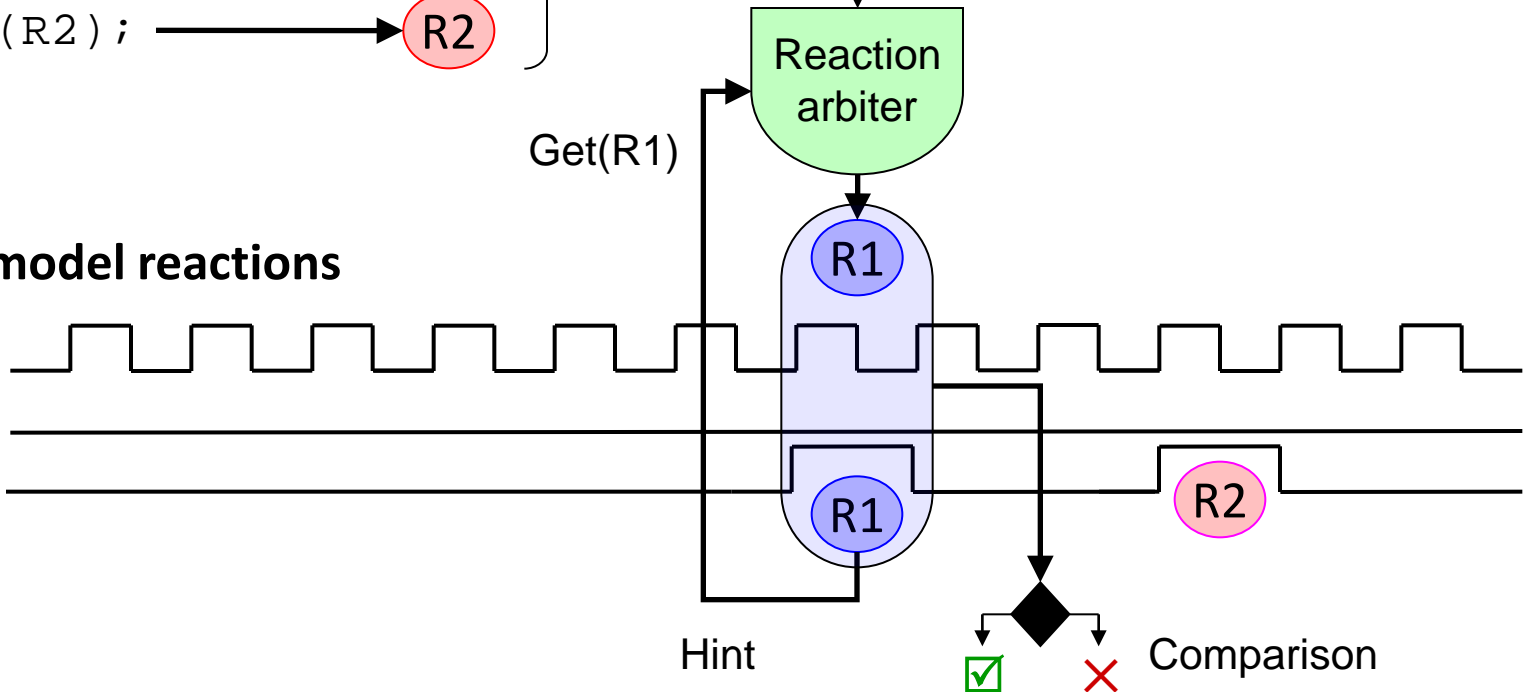


Adaptive arbiter

Reference model reactions

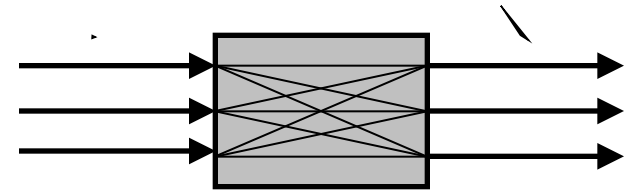
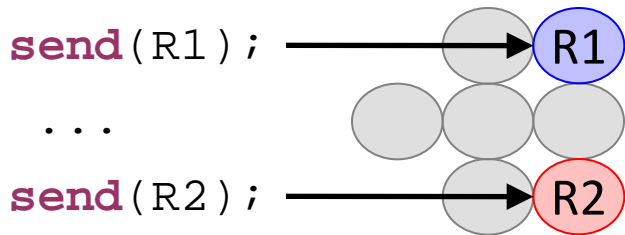


HDL-model reactions



Two-level arbiter

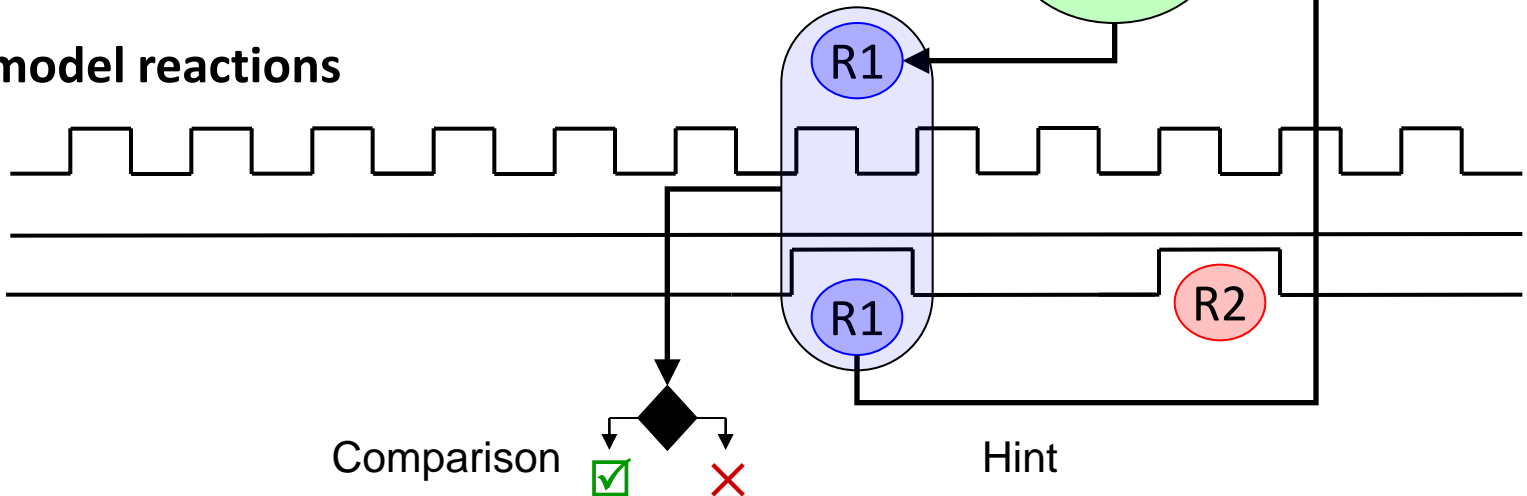
Reference model reactions



Candidates

Partially known order

HDL-model reactions



Timed word (Alur & Dill, 1994)

Σ – alphabet of events

\mathbf{T} – time domain ($\mathbf{R}^{\geq 0}$ or \mathbf{N})

$w = (a_0, t_0)(a_1, t_1), \dots \in (\Sigma \times \mathbf{T})^{\omega(*)}$

- $\forall i . t_i < t_{i+1}$ ($t_i \leq t_{i+1}$) – monotonicity
- $\forall T \exists i . t_i > T$ – progress (if $|w| = \infty$)

Mazurkiewicz trace (1977)

Σ – alphabet of events

$I \subset \Sigma \times \Sigma$ – relation of independence

Equivalent: $u \equiv v \Leftrightarrow u$ is derived from v by means of reordering of closest independence events

Trace is a class of equivalence of event chains in respect to equivalent relation \equiv

Mazurkiewicz trace (1977) - Example

$$\Sigma = \{ a, b, c, d \}$$

$$\mathbf{I} = \{ (a, b), (c, d) + \text{symmetry} \}$$

$$[ab]_{\equiv} = \{ ab, ba \}$$

$$[bc]_{\equiv} = \{ bc \}$$

$$[abcd]_{\equiv} = \{ abcd, bacd, abdc, badc \}$$

Partially ordered set – Pratt (1982)

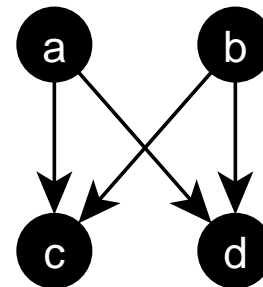
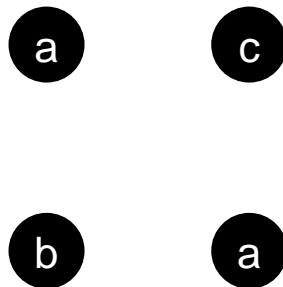
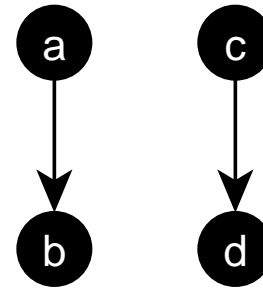
Σ – alphabet of events

Pomset is tuple $\langle \mathbf{V}, \leq, \lambda \rangle$

- \mathbf{V} – set of vertexes
- $\leq \subset \mathbf{V} \times \mathbf{V}$ – partial set
- $\lambda: \mathbf{V} \rightarrow \Sigma$ – labeling function

Partially ordered set – Pratt (1982)

Examples



Timed trace – Chieu & Hung (2012)

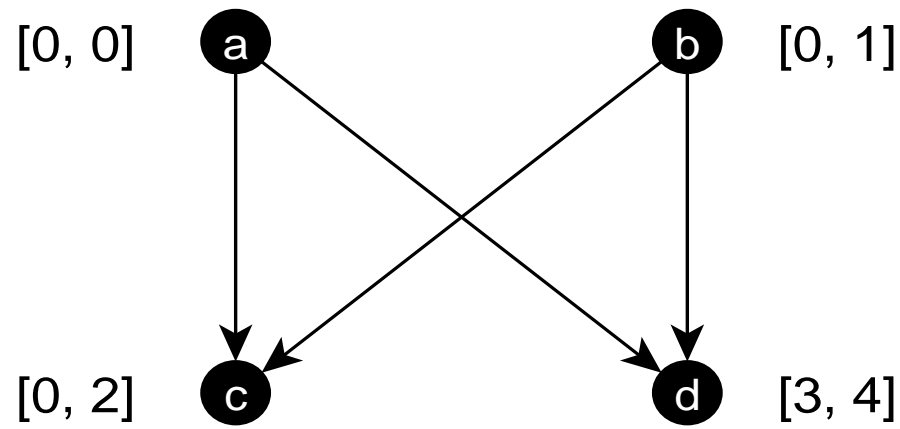
Σ – alphabet of events, \mathbf{T} – time domain

Timed trace – $\langle \mathbf{V}, \leq, \lambda, \theta [, \delta] \rangle$

- \mathbf{V} – set of vertexes
- $\leq \subset \mathbf{V} \times \mathbf{V}$ – partial order
- $\lambda: \mathbf{V} \rightarrow \Sigma$ – labeling function
- $\theta: \mathbf{V} \rightarrow \mathbf{T}$ – time of event
- $\delta: \mathbf{V} \rightarrow \Delta \mathbf{T}$ – allowed interval

Timed trace – Chieu & Hung (2012)

Examples



- { abcd, bacd, abdc, badc }
- { abcd, bacd } – time restrictions

Behavior of specification and implementation

Implementation behavior

$$\langle \mathbf{V}_I, \emptyset, \lambda_I, \theta_I \rangle$$

Specification behavior

$$\langle \mathbf{V}_S, \leq, \lambda_S, \theta_S, \delta_S \rangle$$

Allowed time interval

$$\delta_S(x) = [\theta_S(x) - \Delta t(x), \theta_S(x) + \Delta t(x)]$$

Correspondence of events

$$\mathbf{match}(x, y) = (\lambda_I(y) = \lambda_S(x)) \ \& \ (\theta_I(y) \in \delta_S(x))$$

Conformance relation

$$I \sim S \Leftrightarrow \forall t \in \mathbf{T} .$$

$$\exists \mathbf{M} \subseteq \{ (x, y) \in \mathbf{past}_S(t) \times \mathbf{past}_I(t) \mid \mathbf{match}(x, y) \}$$

- \mathbf{M} – one-to-one relation
- $\forall x \in \mathbf{past}_S(t - \Delta t) \exists y \in \mathbf{past}_I(t) . (x, y) \in \mathbf{M}$
- $\forall y \in \mathbf{past}_I(t - \Delta t) \exists x \in \mathbf{past}_S(t) . (x, y) \in \mathbf{M}$
- $\forall (x, y), (x', y') \in \mathbf{M} . x \leq x' \Rightarrow \theta(y) \leq \theta(y')$

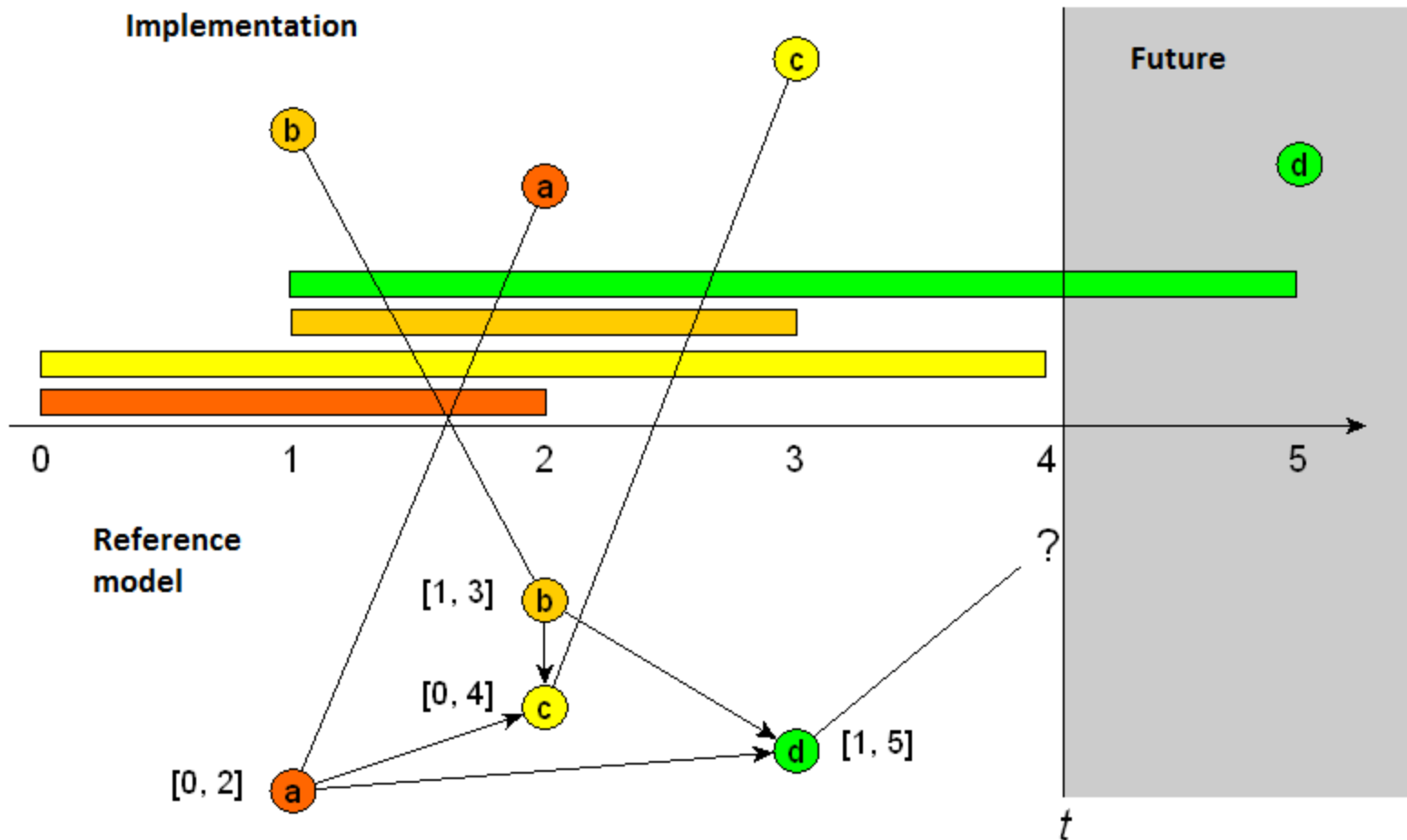
Reaction arbiters

$$\mathbf{arbiter}_1 = \min_{\leq}(X)$$

$$X \subseteq \mathbf{V}_S$$

$$\mathbf{arbiter}_2(y, X) = \begin{cases} x, & \exists x \in X . \mathbf{match}(x, y) \\ \epsilon, & \nexists x \in X . \mathbf{match}(x, y) \end{cases}$$
$$y \in \mathbf{V}_I, X \subseteq \mathbf{V}_S$$

Conformance relation checking



C++TESK Testing ToolKit

Web: <http://forge.ispras.ru/projects/cpptesk-toolkit>


E-mail: cpptesek-support@ispras.ru

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Files

File ▲	Date	Size	D/L
 1.0			
cpptesek-toolkit-1.0.1-beta-110415.tar.gz	04/15/2011 04:17 pm	2.1 MB	12
cpptesek-toolkit-1.0.2-beta-110504.tar.gz	05/04/2011 03:14 pm	2.6 MB	6
cpptesek-toolkit-1.0.3-beta-110510.tar.gz	05/10/2011 10:32 pm	4 MB	8
cpptesek-toolkit-1.0.4-beta-110520.tar.gz	05/20/2011 07:31 pm	5.9 MB	5
cpptesek-toolkit-1.0.5-beta-110528.tar.gz	05/28/2011 07:22 pm	6.5 MB	3
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cpptesek-toolkit-1.0.7-beta-110625.tar.gz	06/25/2011 07:10 pm	7.5 MB	1
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cpptesek-toolkit-src-1.0.7-beta-110625.tar.gz	06/25/2011 07:10 pm	10 MB	7

Conclusion

- Based on the theory of traces and partially ordered multisets method of on-the-fly analysis of hardware systems has been developed
- The method has been implemented in C++TESK Testing ToolKit and has been successfully used in a number of projects
- Future research is connected with failure diagnostics: giving hints to localization of bugs

THANK YOU

- Any questions?